

**Lecture 4: Filtrations and Stopping Times***Lecturer: Ioannis Karatzas**Scribes: Heyuan Yao***4.1 Filtrations**

Consider a measurable space  $(\Omega, \mathcal{F})$ , where  $\Omega$  is a non-empty "sample space" and  $\mathcal{F}$  is a  $\sigma$ -algebra of subsets of  $\Omega$  ("events"), as well as an increasing sequence

$$\{\emptyset, \Omega\} =: \mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \mathcal{F}_2 \subseteq \dots \subseteq$$

of  $\sigma$ -algebras of  $\mathcal{F}$ .

Typical situation: sequence  $X_1, X_2, \dots$  of (real-valued)  $\mathcal{F}$ -measurable functions on  $\Omega$ , a.k.a. "random variables", successive outcomes of an experiment that we monitor on a day-to-day basis. Then

$$\mathcal{F}_n = \sigma(X_1, \dots, X_n),$$

the smallest  $\sigma$ -algebra w.r.t. which the vector  $(X_1, \dots, X_n)$  is measurable, has the significance of information accumulated by day  $t=n$ .

We call **filtration** the collection

$$\mathbb{F} = \{\mathcal{F}_n\}_{n \in \mathbb{N}_0}$$

and introduce also the "ultimate"  $\sigma$ -algebra

$$\mathcal{F}_\infty := \sigma\left(\bigcup_{n \in \mathbb{N}_0} \mathcal{F}_n\right)$$

the information that "accrues all the way to the end of time".

Given a filtrated measurable space  $(\Omega, \mathcal{F})$ ,  $\mathbb{F}$  as just described, we say that a sequence of measurable functions  $Y_1, Y_2, \dots$  on  $(\Omega, \mathcal{F})$  is

- **adapted to  $\mathbb{F}$** , if  $Y_n$  is  $\mathcal{F}_n$ -measurable,  $\forall n \in \mathbb{N}$ .

In the "canonical" case, where  $\mathbb{F}$  is generated by  $\{X_n\}_{n \in \mathbb{N}}$ , this means

$$Y_n = f_n(X_1, \dots, X_n), \quad \forall n \in \mathbb{N}$$

for some measurable  $f_n : \mathbb{R}^n \rightarrow \mathbb{R}$ .

- **predictable w.r.t.  $\mathbb{F}$**  if  $Y_n$  is  $\mathcal{F}_{n-1}$ -measurable,  $\forall n \in \mathbb{N}$ .

In the "canonical" case,

$$Y_n = g_n(X_1, \dots, X_{n-1}), \quad \forall n \in \mathbb{N}$$

for some measurable  $g_n : \mathbb{R}^{n-1} \rightarrow \mathbb{R}$ .

## 4.2 Stopping Time of $\mathbb{F}$

A measurable mapping  $T : \Omega \rightarrow N_0 \cup +\infty$  with the property

$$\{T \leq n\} \in \mathcal{F}_n, \quad \forall n \in \mathbb{N} \tag{4.1}$$

is called a **stopping time** of  $\mathbb{F}$ .

Exercise: (4.1) is equivalent to

$$\{T = n\} \in \mathcal{F}_n, \quad \forall n \in \mathbb{N}.$$

Prime Example: First Hitting Time of  $A \in \mathcal{B}(\mathbb{R})$

$$H_A := \begin{cases} \min\{n \in \mathbb{N} : Y_n \in A\} \\ \infty, \text{ if } \{n \in \mathbb{N} : Y_n \in A\} = \emptyset \end{cases}$$

for some  $Y_1, Y_2, \dots$  adapted to  $\mathbb{F}$ . This is because

$$\{H_A = n\} = \{Y_1 \notin A, Y_2 \notin A, \dots, Y_{n-1} \notin A, Y_n \in A\} \in \mathcal{F}_n, \quad \forall n \in \mathbb{N}.$$

### 4.2.1 Algebra of Stopping Times

(i) if  $S, T, \{T_n\}_{n \in \mathbb{N}}$  are stopping times, then so are

$$S + T, S \wedge T, S \vee T, \sup_n T_n, \inf_n T_n, \limsup_{n \rightarrow \infty} T_n, \liminf_{n \rightarrow \infty} T_n,$$

and of course  $\lim_{n \rightarrow \infty} T_n$  whenever it exists.

(ii) The fixed time  $T = m$  (some  $m \in \mathbb{N}$ ) is a stopping time.

(iii) The difference  $T - S$  is in general NOT a stopping time.

For instance,  $H_A - 1$  is NOT a stopping time:

$$\{H_A - 1 = m\} = \{H_A = m + 1\} = \{Y_1 \notin A, Y_2 \notin A, \dots, Y_m \notin A, Y_{m+1} \in A\} \notin \mathcal{F}_n,$$

in general.

Likewise, the time

$$D_A := \begin{cases} \max\{n \in \mathbb{N}_0 : Y_n \in A\} \\ 0, \text{ if } \{n \in \mathbb{N} : Y_n \in A\} = \emptyset \end{cases}$$

of last visit in a given set  $A \in \mathbb{B}(\mathbb{R})$  by some  $\mathbb{F}$ -adapted sequence  $Y_0, Y_1, Y_2, \dots$  is in general NOT an  $\mathbb{F}$ -stopping time:

$$\{D_A = m\} = \{Y_m \in A, Y_{m+1} \notin A, Y_{m+2} \notin A, \dots\} \notin \mathcal{F}_m,$$

in general.

### 4.2.2 $\sigma$ -algebra of Events Revealed up until a Stopping Time T

For a given "date" (trivial stopping time)  $T = m$ , we have  $\mathcal{F}_t = \mathcal{F}_m$  as the information accumulated up until  $T$ . Can we generalize this notion to arbitrary stopping times?

Yes, as follows:

$$\mathcal{F}_T := \{A \in \mathcal{F} : A \cap \{T \leq n\} \in \mathcal{F}_n, \forall n \in \mathbb{N}_0\} = \underline{\{A \in \mathcal{F} : A \cap \{T = n\} \in \mathcal{F}_n, \forall n \in \mathbb{N}_0\}} \quad (\text{Exercise})$$

Here are a few consequences of this definition, that should be checked very thoroughly.

1. The thus defined collection of events is a  $\sigma$ -algebra, with respect to which  $T$  is measurable.
2.  $\mathcal{F}_T = \mathcal{F}_m$ , if  $T \equiv m$ .
3. If  $S \leq T$  are  $\mathbb{F}$ -stopping times, then

$$\mathcal{F}_S \subseteq \mathcal{F}_T.$$

4. For arbitrary stopping time  $S, T$  we have

$$\mathcal{F}_{S \wedge T} = \mathcal{F}_S \cap \mathcal{F}_T.$$

5. The events  $\{S < T\}, \{S > T\}, \{S = T\}$  belong to  $\mathcal{F}_{S \wedge T}$ .

For any  $\mathbb{F}$ -adapted sequence  $(Y_n)_{n \in \mathbb{N}_0} = \mathcal{Y}$  and ANY random variable  $T : \Omega \rightarrow \mathbb{N}_0 \cup \{+\infty\}$ , we define

$$Y_T := \sum_{k \in \mathbb{N}_0} Y_k \mathbb{I}_{\{T=k\}} + (\limsup_{n \rightarrow \infty} Y_n) \mathbb{I}_{\{T=\infty\}}$$

"the value of the sequence at the random time  $T$ ", as well as the new random sequence

$$Y_{T \wedge n}, n \in \mathbb{N}_0$$

"the random sequence  $\mathcal{Y}$ , stopped at time  $T$ ."

#### Exercise:

Check that, if  $T$  is a stopping time, then

- (i) the random variable  $Y_T$  is  $\mathcal{F}_T$ -measurable,
- (ii) the random sequence  $(Y_{T \wedge n})_{n \in \mathbb{N}_0}$  is adapted to  $\mathbb{F}$ .